

Ionospheric Monitoring Experimentation Plan and Instrument Development

MONITOR TN2230-40-50 DRAFT

Research group of Astronomy & Geomatics **Technical University of Catalonia**

EXTERNAL UPC PRODUCTS:

"TOMION TEC MAP PROVISION", "GEODETIC PREPROCESSING AND IONOSPHERIC TRUTHS" AND "PRELIMINARY PERTURBATION ANALYSIS BASED ON IGS DATA"

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1 INTRODUCTION

1.1 PURPOSE

The main purpose of this report is to summarize the results of the following MONITOR WPs: WP2230 "External Product - TOMION TEC map provision", WP2240 "Geodetic preprocessing and Ionospheric Truths" and WP2250 "External Product - Preliminary Perturbation Analysis based on IGS data", following the WPDs included in the MONITOR proposal, pages 13-32, 13-33 and 13-34, updated with the decision agreed in delta-PDR meeting.

1.2 DISTRIBUTION OF THE DOCUMENT

After a first section containing the main characteristics of the UPC external products in tabular format (content, messages, format, plots, sampling, latencies), a short practical description is given for each UPC external product, including the needed references and examples of plots to be provided to CAPF.

2 MAIN CHARACTERISTICS OF MONITOR UPC EXTERNAL IONOSPHERIC PRODUCTS

Table 1: Main characteristics of the UPC external ionospheric products for project MONITOR.

| | | ,hh,mm,ss | | |
|-------------|---------------------|----------------|----------------------------------|---------------------------------|
| MUIT | lonospheric | year, doy, tse | printf "%4d %3d %5d %4s %2d | "itsvar- |
| | truth: observed | c,rec,prn,ele | %8.3f %13.3f %13.3f %13.3f | "XXXX"."YYYY"."DDD" |
| | STEC referred | ,xrec,yrec,zr | %13.3f %13.3f %13.3f %4d %3d | .muit" where XXXX is |
| | STEC to | ec,xtra,ytra, | %8.3f %13.3f %13.3f %5d | 4-digits IONEX the |
| | measured at | ztra,year_el | %13.3f %10.3f %4s %10.3f\n" | files id, DDD is the day |
| | highest | emax, doy_el | | of year YYYY (e.g. |
| | elevation line- | emax,tsec_e | | itsvar- |
| | of-sight for the | lemax, elema | | uqrg.2010.324.muit) |
| | phase same | x,xtra_elem | | |
| | continuous | ax,ytra_ele | | |
| | transmitter- | max,ztra_el | | |
| | receiver arc (in | emax,dSTE | | |
| | TECU _s) | C_obs,iaac, | | |
| | | dSTEC_iaac | | |
| | | ,const," | | |
| | | MUIT00" | | |

Table 2: Messages and details, corresponding to UPC external ionospheric products.

Table 3: Fields and explanation, all of them included in the messages corresponding to UPC external products.

Table 4: Table containing the plots to be provided as companion of the UPC external ionospheric products.

3 GLOBAL VTEC MAPS WITH THE TOMOGRAPHIC IONOSPHERE MODEL,TOMION (VTEC-TOMION, UPC)

The development of the tomography approach used in the TOMographic IONosphere model (TOMION) was started at UPC in the second half of the 1990s [Hernández-Pajares et al., 1997, 1999; Juan et al., 1997]. At that time, the main focus was to assess the feasibility of computing better TEC maps with a coarse tomography algorithm. TOMION has since been developed to provide several versions which are able to process ground based GNSS ionospheric data, GNSS LEO radio occultation data [Hernández-Pajares et al., 1998, 2000a], GNSS geodetic data [Hernández-Pajares et al., 2000b], and ionosonde data [García-Fernandez et al., 2003]. In real-time processing it is also possible to provide corrections for precise user positioning (Wide Area RTK, see Hernández-Pajares et al. [2002, 2010]. Since 1998, TOMION has been used in the UPC Ionospheric Analysis Centre for the IGS [Hernández-Pajares et al., 2009].

Figure 1: 2-layer voxel model typically used in TOMION with ground-based GNSS data.

The version of TOMION used in this study (v1.5) generates Global Ionospheric Maps (GIMs) of vertical TEC (vTEC) and includes an interpolation module using Kriging interpolation [Orús et al., 2005]. The ionosphere is represented by two or more layers of voxels (see [Figure 1](#page-17-1)). In each voxel the electron density is assumed to be constant. No background model is used and the overall accuracy is better than 80% in the worst case (Solar Maximum and over the oceans with few and isolated receivers, see Figure 14d in Hernández-Pajares et al. 2009). The assimilation of data proceeds in three steps: 1) an initial fit is made to the ground based TEC data; 2) data gaps are filled using a modified Kriging interpolation technique to generate GIMs, taking into account the correlation lengths of the vTEC errors in the interpolation process, specially important in ocean and southern hemisphere regions with sparse groundbased GPS data available. And 3) an enhanced Abel Transform retrieval can be addititonally used to produce high accuracy and high resolution electron density fields in the vicinity of radio occultation measurements, by taking the previous vTEC as proxy of the horizontal gradients in the occultation region. Presently new optimized versions of TOMION, for realtime and predicted VTEC maps, are continuously running in the context of IGS real-time and ionospheric working groups, respectively.

Figure 2: Example of VTEC map plot associated to VTEC-TOMION UPC external products for day 325 of 2010, 1200h GPS time (file uqrg10325.1200.tec0.global.gif, see [Table 4](#page-16-0) for details).

4 DELAY CODE BIASES OF GPS TRANSMITTERS (TDCBS-TOMION, UPC)

The Satellite Delay Code Biases of P1-P2 are being computed as well by TOMION, as a derived product from the VTEC global maps. Indeed, the ionospheric carrier phase is aligned with the pseudorange, estimating the corresponding ambiguity by averaging with the ionospheric pseudorange for every phase continuous arc of data. The resulting values can be considered directly Slant TEC (STEC) excepting for the receiver and transmitters DCB values, which are then estimated by averaging the "post-fit residual" after substracting the STEC prediction given by the global VTEC model, previously calculated. The DCBs for the GPS satellites or transmitters are obtained, after substracting the average of the DCBs between them (which constitutes the receiver DCB, see next section). The values of the transmitters are quite stable, typically at the level of few tenths of ns (see for instance Hernández-Pajares et al. 2009), as it can be seen in particular for recent datasets in [Figure 3](#page-19-1) and [Figure 4.](#page-20-0)

Figure 3: Example of GPS transmitter DCB values associated to TDCBs-TOMION UPC external products for day 324 of 2010 (file tdcbs-uqrg.2010.324.mutd.gps.snapshot.gif, see [Table 4](#page-16-0) for details).

Figure 4: Same plot than previous one, but based on the GPS transmitter DCB estimation provided by a different IGS ionospheric analysis center (CODE, day 324 of year 2010).

5 DELAY CODE BIASES OF GPS RECEIVERS (RDCBS-TOMION, UPC)

The Receiver Delay Code Biases of P1-P2 are similarly computed to the transmitter ones, described in previous section, as the between-transmitter-average DCBs affecting the given receiver. The values of the receiver DCBs are stable typically at the level of up to few ns (see for instance Hernández-Pajares et al. 2009). You can see recent estimates for some IGS receivers in [Figure 3.](#page-19-1)

Day 324 of 2010, DCBs from ugrg ref. to AAT

Figure 5: Example of GPS receiver DCB values associated to RDCBs-TOMION UPC external products for day 324 of 2010 (file rdcbs-uqrg.2010.324.murd.gps.snapshot.gif, see [Table 4](#page-16-0) for details).

6 SLANT TOTAL ELECTRON CONTENT VALUES (STECS-TOMION, UPC)

The Slant Total Electron Content along the GPS transmitter-receiver line-of-sights (LOS) is another derived product from the VTEC-TOMION maps. Indeed, the STEC values directly given by TOMION for the LOS are used as reference to estimate the ionospheric phase ambiguities from the receiver measurements. Then they can be affected by errors of few TECU in well covered mid latitude regions (such as Europe) up to less than 20 TECU in isolated low latitude regions in Solar Maximum conditions when the data of the used receiver have not taken part in the computation of the global VTEC map. You can see a recent example in [Figure 6.](#page-22-1)

Figure 6: Example of STEC values associated to STECs-TOMION UPC external product for a 24 hours window corresponding to day 202 of 2010 (file stecs-igrg.2010.201- 203.acor.window005.must.gif, see [Table 4](#page-16-0) for details).

7 GLOBAL ELECTRON CONTENT (GEC-TOMION, UPC)

The Global Electron Content, GEC is a single global ionospheric index proposed by Astafyeva et al. 2006. It is computed from the integration of each given VTEC map on the overall Ionosphere surface (in which the free electrons distribution is approximated). The associated unit is called Global Electron Content Unit, or GECU, defined as 10 32 electron/m².

Figure 7: Example of daily GEC evolution, given in the GEC-TOMION UPC external product for day 324 of 2010 (file gec-uqrg.2010.324.muge.gif, see [Table 4](#page-16-0) for details).

8 GNSS SOLAR FLARE DETECTOR IN REAL-TIME (GSFLAD, UPC)

The availability of a global network of GNSS receivers monitoring simultaneously the daylight and night hemispheres, makes feasible the detection of the main Solar Flares through the rapid overionization of the Ionosphere by means of a single GNSS Solar Flare Detector (GSFLAD, see in particular García-Rigo et al. 2007, and its monitoring previous to the Halloween storm in [Figure 8\)](#page-24-1).

Figure 8: Evolution of GSFLAD index, to be provided by UPC as external MONITOR product, for the big flare triggering the Halloween ionospheric storm, during the day 301 of 2003 (file gsflad.2003.301.musf.gif, see [Table 4](#page-16-0) for details).

9 SIDEREAL DAY-TO-DAY TOTAL ELECTRON CONTENT VARIABILITY (SDTVAR, UPC)

The direct computation of sidereal day-today total electron content variability (SDTVAR) from ground-based GPS data, was proposed in [Hernández-Pajares et al. 1997] as a simple way of increasing the accuracy in the computation of electron content variation. Indeed thanks to the repeatability of the transmitter-receiver geometry after every sidereal day, an efficient implicit filtering of pseudorange multipath and DCB intradaily variability is got after taking sidereal-day-to-day differences. This allows for instance to monitor ionospheric storm effects on electron content (see above mentioned reference) or increasing the detectability of Solar Flare events (Liu et al. 2004). A recent example can be found in

Figure 9: SDTVAR based detection of one ionospheric perturbantion seen from four permanent GPS stations in NorthAmerica (ordered from West to East), during days 18 and 19 October 1995, referred

to day 17 October (y-axis: VTEC variation in approx. tens of TECU, x-axis time in hours, referred to 18 October 0000 GPS time –source: [Hernández-Pajares et al. 1997]-).

Figure 10: Example of VTEC variation corresponding to the SDTVAR UPC external products for day 344 of 2010 (file rdcbs-uqrg.2010.324.murd.gps.snapshot.gif, see [Table 4](#page-16-0) for details).

10 SINGLE RECEIVER MEDIUM SCALE TRAVELLING IONOSPHERIC DISTURBANCE INDEX FOR MID LATITUDES (SRMTID, UPC)

The Single Receiver Mid-Latitude Medium Scale Travelling Ionospheric Disturbance (SRMTID) was initially introduced in [Hernández-Pajares et al. 2006a] (Figure 15), in order to easily indicate in real-time the Medium Scale TID (MSTID) activity for mid latitude stations, in real-time and without the need of a local network (as it is needed for determining the MSTID propagation parameters, see [Hernández-Pajares et al. 2006b]). The SRMTID index is defined as the RMS of the STEC rate drift, very precisely deduced from the ionospheric phase for all the satellites in view for a given epoch. It is actually computed as double difference in time, each 300 seconds, to filter out larger periods much larger than those of MSTID (around 1000 seconds).

In detail the algorithm can be summarized in the following way, for each given pair of GNSS satellite-receiver independently:

1) The ionospheric combination, Li, is computed from the L1 and L2 GNSS carrier phases in length units:

 $Li=LI-L2$

2) The cycle-slips are hopefully detected and marked, for instance looking for values of double consecutive difference in time of Li, $|d^2$ Li $| = |$ Li(t+dt)-2Li(t)+Li(t-dt) $| >$ d2Li_threshold (for instance d2Li threshold= 0.10 meters +0.002 meters/sec*(dt/sec))

3) For every time t with measurements, with no cycle slip regarding to the previous and later observations, separated each consecutive pair by dt=30 seconds, d2Li is computed.

4) The RMS of 10 consecutive d2Li values at 30 seconds, i.e. each 300 seconds, is computed, given the SRMTID index:

$$
SRMTID \quad [t] = \sqrt{\sum_{j=0}^{9} (d \, 2Li\left[t - j \ast 30 \text{ sec}\right])^2}
$$

An example can be seen in [Figure 11,](#page-28-0) showing the typical mid-latitude MSTID activity around local winter and noon (see [Hernández-Pajares et al. 2006b] for a full study). SRMTID can contain, especially at high or low latitude, part of the power due to shorter periods, as scintillation activity.

Figure 11: Example of SRMTID index (other external MONITOR product provided by UPC) corresponding to receiver EBRE during day 344 of 2003 (file srmtid.2003.344.mumt.ebre.gif, see [Table 4](#page-16-0) for details).

11 RATE OF TOTAL ELECTRON CONTENT INDEX (ROTI, UPC)

The standard deviation of the TEC-rate (Rate-Of-TEC-Index, ROTI) is commonly calculated over a 5 minutes interval. For this task 30s-GNSS-receiver data is sufficient. As it was indicated in the output of MONITOR WP1200, different authors have compared it with direct amplitude measurements, suggesting that ROTI measurements can be a low-cost substitute for high-rate measurements allowing monitoring large areas. However it must be taken into account that it can be contaminated by variability components with periods of several seconds, likely due in some scenarios to phase multipath or interference. An example of ROTI evolution during a whole day can be seen in [Figure 12\)](#page-29-1).

Figure 12: Example of ROTI evolution (additional external UPC product for MONITOR), for IGS receiver EBRE during the day 344 of 2003 (file roti.2003.344.muro.ebre.gif, see [Table 4](#page-16-0) for details).

12 IONOSPHERIC TRUTH: SLANT TOTAL ELECTRON VARIATION ALONG A CONTINUOUS ARC OF GNSS CARRIER PHASE (ITSVAR, UPC)

The GPS ionospheric carrier phase difference, for a given LOS, regarding to the value corresponding to the higher elevation ray in the phase continuous arc of data, provides a very precise ionospheric truth of the STEC variation, in space an time (typically much accurate than 0.1 TECU). This Ionospheric Truth of Slant Total Electron Variation can be used to compare the performance of ionospheric models. An example of ITSVAR can be seen in [Figure 13\)](#page-30-1)

Figure 13: Example of STEC variation Ionospheric Truth daily evolution (ITSVAR external UPC product) for IGS receiver EBRE, during day 201 of 2010 (file itsvar.2010.201.ebre.muit.gif, see [Table](#page-16-0) [4](#page-16-0) for details).

13 CONCLUSIONS

A summary of the external products, in which gAGE/UPC is contributing to MONITOR, is provided.

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14.1 APPLICABLE DOCUMENTS

Table 5: Applicable Documents

14.2 REFERENCE DOCUMENTS

Table 6: Reference Documents

Annex 1 List of Acronyms

A1.1 Acronyms

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